# Research Article Independent Component Analysis of Functional Magnetic Resonance Imaging (fMRI) Data: A simple Approach

<sup>1</sup>Amir, A. Khaliq, <sup>2</sup>I.M. Qureshi, <sup>1</sup>Ihsanulhaq and <sup>1</sup>Jawad A. Shah <sup>1</sup>Department of Electronic Engineering, International Islamic University, Islamabad, Pakistan <sup>2</sup>Air University, ISSS, Islamabad, Pakistan

Abstract: Independent Component Analysis (ICA) separates spatial and temporal components of fMRI data which may consist of activation patterns, cardiac and respiratory tasks and other artifacts. In this study sources of (fMRI) data are separated using ICA based on simple fixed point iteration method and steepest ascent method. Both are the simplest methods used in optimization. However in this study complete matrix W (un-mixing matrix) is updated in each iteration instead of vector based updating of W. This makes the source separation process very fast. Simulated fMRI data is processed using the proposed method and the results are compared with other ICA approaches in terms of speed and accuracy.

Keywords: Blind source separation, fMRI, ICA

#### INTRODUCTION

Functional fMRI is a tool used for measuring the functionality of the brain by measuring the oxygenation in the blood flow (Pekar, 2006). Usually experiments are performed for fMRI data acquisition, which are based on a block design comprising cycles of activity and non-activity. During such experiments signals from thousands of brain voxels are taken every few seconds, thus forming a complicated time series of mixtures comprising of task activated, non-activated, transiently task activated, respiratory and cardiac functions activated voxels (Martin et al., 1998). Also the intensity of the activated voxels is too low, normally in the range of 10-15% of variance at 1.5T scanner. This low SNR data is normally first de-noised using some special techniques (Amir et al., 2012). Thus extraction of activated voxels from this complicated mixture of data is a very challenging statistical task.

Changes in fMRI signal, including Blood Oxygen Level Dependent (BOLD) are detected using different techniques including subtraction, correlation, time frequency analysis, Principal component analysis (PCA) and ICA etc.

In subtraction or in general correlation based techniques (Bandettini *et al.*, 1993), the voxels which are responsible for activation of the experimental task are extracted using a priori knowledge of the task related model. A correlation of the experimental model and each time course is performed and the spatial contents are termed as active regions in case of strong correlation results. Other approaches including Statistical Parametric Mapping (SPM) (Friston, 1995) uses t-test and f-tests which are uni-variate methods. In time frequency analysis (Mitra et al., 1997), fMRI signals are recorded in frequency domain. This type of analysis is based on the fact that different experimental task related and function related voxels time courses exhibit different frequencies and thus can be distinguished. PCA is another technique used for fMRI analysis (Moeller and Strother, 1991). This technique finds the orthogonal Eigen-images having the greatest variance in the data. Normally the numbers of principal components representing the data with a specific accuracy are less than the actual dimension of the data. Thus PCA can be used for dimension reduction as well. ICA is another technique which is also used for source separation of fMRI as suggested by (Martin et al., 1998; McKeown et al., 1998) and others. ICA is a statistical method which can convert a multidimensional vector into components which are statistically independent (McKeown, 1998), thus making it useful for blind source separation problem and is widely used in other fields as well (Zhiguo et al., 2006; Hong-Bin et al., 2008; Yu and Cheng, 2012).

In this study fMRI data sources are separated using ICA with a matrix based updating rule which makes the updating process very fast. The proposed techniques prove to be efficient in terms of processing time and accuracy on simulated fMRI data.

**ICA model:** ICA model can be described as:

$$X = AS$$
(1)

Corresponding Author: Amir, A. Khaliq, Department of Electronic Engineering, International Islamic University, Islamabad, Pakistan

This work is licensed under a Creative Commons Attribution 4.0 International License (URL: http://creativecommons.org/licenses/by/4.0/).

in which X is the observed data of dimension  $n \times m$ , A is a mixing matrix of dimension n×k and S consist of independent sources of dimension k×m.

ICA problem can now be described as finding the mixing matrix A such that S can be calculated as:

$$\hat{S} = Y = WX \tag{2}$$

and  $W = A^{-1}$ 

20

40 60

20

40 60

20

40 60

20

40 60

20

40 60

20

40 60

20

40 60

20 40

60

where, W is the un-mixing matrix. W can be obtained by optimizing a cost function with some constraint. Commonly used cost functions are based on info-max, maximum likelihood, mutual information and kurtosis etc.

For example if kurtosis is used as a cost function (Aapo et al., 2001), then the cost function needs to be maximized with the constraint  $W^T W = I$ . Since the sources are independent and the kurtosis of non Gaussian sources is non-zero, therefore we need to maximize the kurtosis which is given by:

$$f(W) = E[Y]^4 - 3[E[Y]^2 = E[WX]^4 - 3[E[WX]^2]^2$$
(3)

20

10

10 20

10 20

10 20

10 20

10 20

10 20

10

Different flavors of ICA have been proposed in literature; some of them are Fast-ICA (Aapo and Oja, 1997), JADE (Cardoso, 1999), Extended Info-Max (Lee et al., 1999) and RADICAL ICA (Miller and Fisher, 2003). Further details of these algorithms can be found in the referred literature.

Pre-processing of the data: For implementation of most of the ICA algorithms the observed data needs to be centered (zero mean) and whitened. Centering of the observed data is done by subtracting mean from the observed data Z:

$$X' = Z - E[Z] \tag{4}$$

where, Z the raw is observed data and X'is the centered data

Similarly whitening is done by multiplying the observed data with some whitening matrix V so that the correlation and covariance matrix of Y becomes identity matrix ie  $E[YY^{T}] = I$ . This process is done using the Eigen-decomposition (Aapo et al., 2001) and is given as.



Fig. 1: Sources and corresponding time courses



Res. J. Appl. Sci. Eng. Technol., 5(24): 5494-5502, 2013

Fig. 2: Sources and time courses extracted by DICA







Fig. 3: Sources and time courses extracted by radical based ICA



Fig. 4: Extracted sources and time courses by ICAMS





Res. J. Appl. Sci. Eng. Technol., 5(24): 5494-5502, 2013

Fig. 5: Extracted sources and time courses by Fast ICA



Fig. 6: Extracted sources and Time courses by the steepest ascent (matrix based) method



Res. J. Appl. Sci. Eng. Technol., 5(24): 5494-5502, 2013

Fig. 7: Extracted sources and time courses by the fixed point (matrix based) method

$$X = VX'$$
(5)

where,  $V = ED^{-1/2}E^T$  and  $EDE^T = E[X'X'^T]$ 

Another preprocessing step which is specifically done in case of fMRI due to its high dimensional data is the dimension reduction step. Here we have used Singular Value Decomposition (SVD) as a dimension reduction technique (Aapo *et al.*, 2001).

**Fourth order contrast function ICA:** In this study we are using to maximize the fourth moment of Y as the cost function as suggested by Aapo *et al.* (2001):

$$f(W) = E[Y^4]$$
(6)

For further simplification the expectation operator E is also omitted and it becomes:

$$f(W) = [Y]^4 = [W X]^4$$
(7)

The steepest ascent approach to maximize this function with constraint of  $W^TW=I$  is given by:

$$W(n+1) = W(n) + \partial \left[WX\right]^4 / \partial W$$
(8a)

where,

W(n) = The old value of the un-mixing matrix W W(n+1) = The new value of the un-mixing matrix W X = The observed data matrix

$$W(n+1) = W(n)+4[WA]^{3} X^{T}$$
 (8b)

Another approach is using fixed point iteration method (Aapo, 1999). In the same way as above the method can be implemented on matrices.

To proceed with fixed point iteration method let  $f(W) = [Y^4] = 0$ . Now adding W on both sides leads to  $W(n+1) = W(n) + [Y^4]$ . But since we are dealing with matrices therefore care should be taken about the dimensions of the matrices. It is evident in the above equation that we are updating the matrix W while the last term is basically the multiplication of the matrix W with the data i.e., X. Since we need that specific W which gives us f(W), therefore we must multiply the last term by  $X^T$  thus getting the required form of the update equation:

$$W(n+1) = W(n) + [WX]^4 X^T$$
 (9)

It should be noted that +ve sign here indicates that we are maximizing the function.

It should also be noted that W and X are matrices and not vectors and all iteration are performed on matrices which makes the process very fast. Otherwise in case of vectors based iteration we have to iterate vector by vector, which is the case in most of the ICA algorithms and thus making them slow.



Fig. 8: (a) Kurtosis of sources vs iteration and (b) Error tolerance vs iteration (steepest ascent matrix based)

### SIMULATION AND RESULTS

For the validity of the proposed schemes, simulated fMRI data of Machine Learning and Signal Processing lab (MLSP) is used which is freely available on the web (Correa *et al.*, 2005). Sources and corresponding time courses are shown in Fig. 1, the corresponding data matrix X consist of 100 images each having 3600 pixels. This makes a  $100\times3600$  data matrix X. Dimension of the data is reduced to  $8\times3600$  using SVD while

Pre-processing (centering and whitening) of this data is done using Eq. (4) and (5). This simulated data is first processed using the depletion based ICA (Ruck *et al.*, 1998) and the extracted sources and time courses are shown in Fig. 2. It can be seen that the quality of the sources extracted is not bad, but the quality of time courses is poor. Figure 3 and 4 shows the sources and extracted time courses by Radical (Miller and Fisher, 2003) and MS based ICA (Molgedey and Schuste,

1994) algorithms. Both these methods results are moderate and took execution time 38 seconds and one second respectively.

Finally the simulated fMRI data is processed using Fast ICA (Aapo and Oja, 1997).

Proposed steepest ascent (matrix based) and Fixed point iteration (matrix based) algorithms respectively. Results are shown in Fig. 5, 6 and 7 having the execution time of 5, 0.8 and 0.6 sec, respectively. Figure 8a and 8b shows the kurtosis vs. iterations and error tolerance vs iterations respectively of the steepest ascent (matrix based) method, while Fig. 9a and 9b shows the kurtosis vs. iterations and error tolerance vs. iterations respectively of Fixed point (matrix based) method. Execution time and correlation analysis of extracted sources and time courses of all the methods are presented in Table 1, which shows that average performance of both steepest ascent (matrix based) and Fixed point (matrix based) is better than ICA methods which are compared in this study.



Res. J. Appl. Sci. Eng. Technol., 5(24): 5494-5502, 2013

Fig. 9: (a) Kurtosis of sources vs iteration and (b) error tolerance vs iteration (fixed point matrix based)

Table 1. Execution time and conclutions of (5/1) sources/ Time courses with the actual (5/1) sources/ Time courses
--

Sources/Algorithm	Time(sec)	S1/T.C	S2/TC	S3/TC	S4/TC	S5/TC	S6/TC	S7/TC	S8/TC
Dica	7.6	0.97/0.35	0.89/0.51	0.68/0.63	0.97/0.24	0.97/0.03	0.19/0.02	0.61/0.48	0.83/0.38
Radicalica	38	0.96/0.66	0.96/0.47	0.05/0.90	0.35/0.86	0.99/0.42	0.87/0.14	0.89/0.53	0.98/0.24
Icams	1.0	0.59/0.20	0.13/0.51	0.99/0.91	0.06/0.46	0.78/0.09	0.43/0.04	0.04/0.09	0.62/0.13
Fastica	5	0.99/0.55	0.97/0.47	0.60/0.93	0.67/0.60	0.97/0.42	0.96/0.32	0.94/0.56	0.97/0.10
Steepest ascent	0.8	0.96/0.95	0.99/0.80	0.61/0.98	0.98/0.99	0.98/0.59	0.98/0.93	0.70/0.81	0.97/0.29
Matrix based)									
Fixed point (Matrix	0.6	0.93/0.95	0.98/0.81	0.70/0.99	0.90/0.97	0.97/0.97	0.98/0.89	0.70/0.83	0.98/0.84
based)									

Legend S sources, TC = time courses

## CONCLUSION

In this study we have presented simple ICA methods (based on steepest ascent and fixed point iteration matrix Based) for the analysis of fMRI data.

These methods are simple and can be implemented on high dimensional data since a dimension reduction step is used before its implementation. Also its convergence time is very less due to its mathematical simplicity and its matrix based updating rules as compared to other conventional ICA methods. Quality performance of these algorithms is also comparatively good as can be seen from Table 1. These method have been tested on simulated fMRI data, however they can be tested on other similar problems.

### ACKNOWLEDGMENT

We would like to acknowledge and thank Machine learning and Signal Processing Lab University of Maryland Baltimore County USA for providing the simulated fMRI like data.

#### REFERENCES

- Aapo, H., 1999. Helsinki university of technology laboratory of computer and information science: Fast and robust fixed-point algorithms for independent component analysis. IEEE T. Neural Networ., 10(3): 626-634.
- Aapo, H. and E. Oja, 1997. A fast fixed point algorithm for independent component analysis. Neural Comput., 9: 1483-1492.
- Aapo, H., J. Karhunen and E. Oja, 2001. Independent Component Analysis. John Wiley & Sons, New York, pp: 504, ISBN: 047140540X.
- Amir, A.K., I.M. Qureshi and J.A. Shah, 2012. Temporal correlation-based spatial filtering of rician noise for functional MRIs. Chinese Phys. Lett., 29(1), DOI: 10.1088/0256-307X/29/1/018701.
- Bandettini, P.A., A. Jesmanowicz, E.C. Wong and J.S. Hyde, 1993. Processing strategies for time-course data sets in functional MRI of the human brain. Magn. Reson. Med., 30(2): 161-173.
- Cardoso, J.F., 1999. High-order contrasts for independent component analysis. Neural Comput., 11: 157-192.
- Correa, N., Y.O. Li, T. Adali and V. Calhoun, 2005. Comparison of blind source separation algorithms for FMRI using a new MATLAB toolbox: GIFT. Proceeding IEEE International Conference Acoust., Speech, Signal Processing (ICASSP), Philadelphia, PA, 5: 401-403.
- Friston, K.J., 1995. Commentary and opinion: II. Statistical parametric mapping: Ontology and current issues. J. Cereb. Blood Flow Metab., 15(3): 361-370.
- Hong-Bin, C., J. Feng and Y. Fang, 2008. Blind extraction of chaotic signals by using the fast independent component analysis algorithm. Chin. Phys. Lett., 25(2): 405-408.

- Lee, T.W., M. Girolami and T.J. Sejnowski, 1999. Independent component analysis using an extended Infomax algorithm for mixed sub-Gaussian and super-Gaussian sources. Neural Comput., 11: 417-441.
- Martin, J.M., M. Scott, G.B. Greg, T.P. Jung, S.S. Kindermann, *et al.*, 1998. Analysis of fMRI data by blind separation into independent spatial components. Hum. Brain Mapp., 6: 160-188.
- McKeown, M.J., S. Makeig, G.G. Brown, T.P. Jung, S.S. Kindermann, A.J. Bell and T.J. Sejnowski, 1998. Analysis of fMRI data by decomposition into independent spatial components. Hum. Brain Mapp., 6: 160-188.
- Mitra, P.P., S. Ogawa, X. Hu and K. Ugurbil, 1997. The nature of spatiotemporal changes in cerebral hemodynamics as manifested in functional magnetic resonance imaging. Magn. Reson. Med., 37: 511-518.
- Miller, E. and J. Fisher, 2003. ICA using spacings estimates of entropy. J. Mach. Learn. Res., 4: 1271-1295
- Molgedey and H. Schuste, 1994. Separation of independent signals using time-delayed correlations. Phys. Rev. Lett., 72(23): 3634-3637.
- Moeller, J.R. and S.C. Strother, 1991. A regional covariance approach to the analysis of functional patterns in positron emission tomographic data. J. Cereb. Blood Flow Metab., 11(2): 121-135.
- Pekar, J.J., 2006. A brief introduction to functional MRI. IEEE Eng. Med. Biol. Mag., 25(2): 24-26.
- Ruck, T., C. Andrzej and A. Shun-Ichi, 1998. A cascade neural network for blind signal extraction without spurious equilibria. IEICE T. Fundamentals Elec. Commun. Comp. Sci., E81(9): 1833-1846.
- Yu, C. and Z. Cheng, 2012. Research and simulation of FECG signal blind separation algorithm based on gradient method. Res. J. Appl. Sci. Eng. Technol., 4(16): 2707-2711.
- Zhiguo, D., T. Ratnarajah, C. Cowan and Y. Gong, 2006. ICA-based semi-blind spatial equalization for MIMO systems. 14th European Signal Processing Conference (EUSIPCO 2006), Florence, Italy, Copyright by EURASIP.